variables/V-color

## Collision Sensor | small payload | QS-7



With moments trip point from 0.3 to 30 Nm. small payload collision sensors will be the most appropriate models for your applications such as pick and place or dispensing.



Repeatability - X, Y 0.013 mm Repeatability - Z 0.013 mm **QS-7** 

Rotational Repeatability	$\pm$ 0.028 $^{\circ}$
Axial Compliance Vertical	1.380 mm
<b>Compliance Angle</b>	5 °
Rotary Compliance	No limit
<b>Torque Trip Point</b>	0.28 - 1.5 Nm
<b>Moment Trip Point</b>	2 0.31 - 1.5 Nm
Weight	0.110 kg
Diameter	40.000 mm
Profile	27.000 mm
<b>Center of Mass</b>	11.000 mm
Average response time	4-7 ms
<b>Dust Protection</b>	Foam collar supplied
Switch	High reliability aircraft snap acting type. UL/CSA approved. Average cycle life : 7 million cycles

**QS-7** 

## **Collision detector QS-7: Protect your equipment with maximum precision**



**Operating conditions** 

**Operating Pressure** 1.0 - 6.0 bar **Operating Temperature** Min. 0°C / Max. 70°C **Notice :** The provided technical data are the higher limits recommended in static condition. To obtain the correct dimensioning of the product, it is necessary to hold account of all the applicable dynamic forces, including the inertia of the manipulator, the configuration of the tools and the external forces applied.

- Dynamically variable collision sensor that operates on air pressure. Breakaway threshold adjusts to match the working force ranges of robot/application
- Non compressive, metal to metal seals for reliable and consistent operation
- Opening of QuickSTOP air chambers at impact, pressure exhaust and switch signal stop the robot





- Senses angular and compressive forces. QuickSTOP's unique design offers protection in X, Y and Z axis
- Linear and angle strokes available to remove the forces from end of arm tooling and robot wrist at trip point
- Performance readiness is monitored by QuickSTOP. When pressurized, the switch indicates that the QuickSTOP is reset in proper position

- Minimize down time, quick reset, no need for recalibration, stopping robots at source of impact allows for easy identification of cause
- Minimize robot and expensive end of arm tooling damage during robot programing. A must for any education or robot training cell
- Easy to implement, simple to adjust pressure levels according application, quick return on investment



## expertise in connectivity